

# Time delays from blended data

Anti Hirv

Tartu Observatory

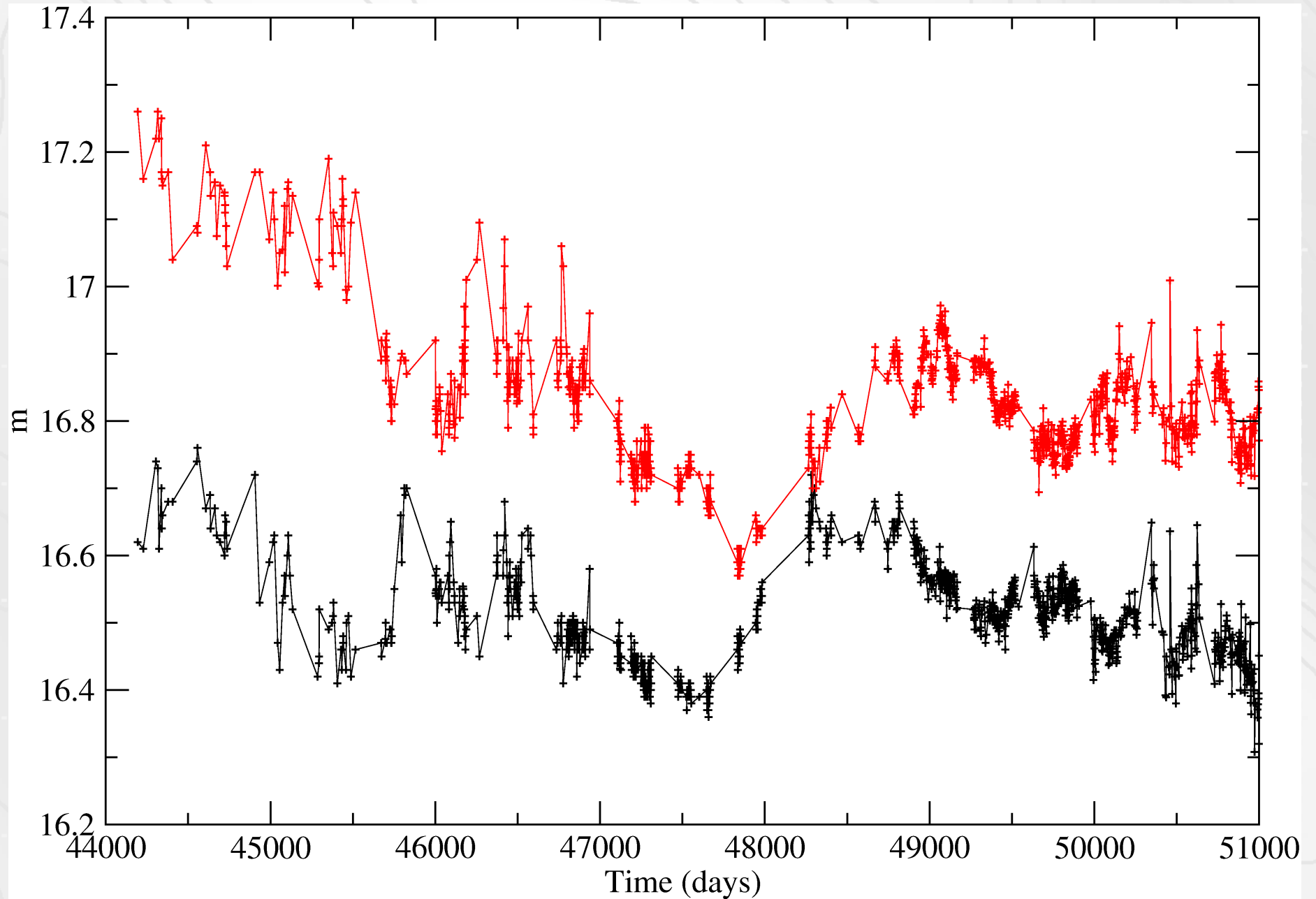
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Summer School 2007: Time Series Analysis

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# Introduction

- Gravitationally lensed quasar images
  - different light paths and flight times -> time delays
- Why are the time delays of lensed quasar images important for us?
- Measuring time delays
  - longtime monitoring -> smaller telescopes -> blended images and blended time series

# Time series of QSO 0957+561



# Two cases of blended light curves

- A clean image and a blend
- Two blended images

Over simplified models:

- continuous curves
- no noise

# Idea of the method for recovering time delays developed by Jaan Pelt et al.

- Compose artificial blend(s) from observed data, using trial delays
- Calculate difference of the curves
- Minimise the difference by varying trial delays

# A clean image and a blend

(continuous case)

Pure curve:  $f_1(t) = a_1 q(t - t_1)$

Blended curve:  $f(t) = f_2(t) + f_3(t) =$   
 $= a_2 q(t - t_2) + a_3 q(t - t_3)$

Artificial blend ->

$$g(t) = f_1(t - \Delta_l) + \alpha f_1(t - \Delta_l - \Delta_s) =$$

$$= a_1 q(t - t_1 - \Delta_l) + \alpha a_1 q(t - t_1 - \Delta_l - \Delta_s)$$

Observed blend  $f(t)$  and artificial blend  $g(t)$   
 are magnified copies of each other if

$$\Delta_l = t_2 - t_1 \quad \Delta_s = t_3 - t_2 \quad \alpha = a_3 / a_2$$

# Two blended images

(continuous case)

Observed blends:

$$g_1(t) = a_1 q(t - t_1) + a_2 q(t - t_2),$$

$$g_2(t) = a_3 q(t - t_3) + a_4 q(t - t_4)$$

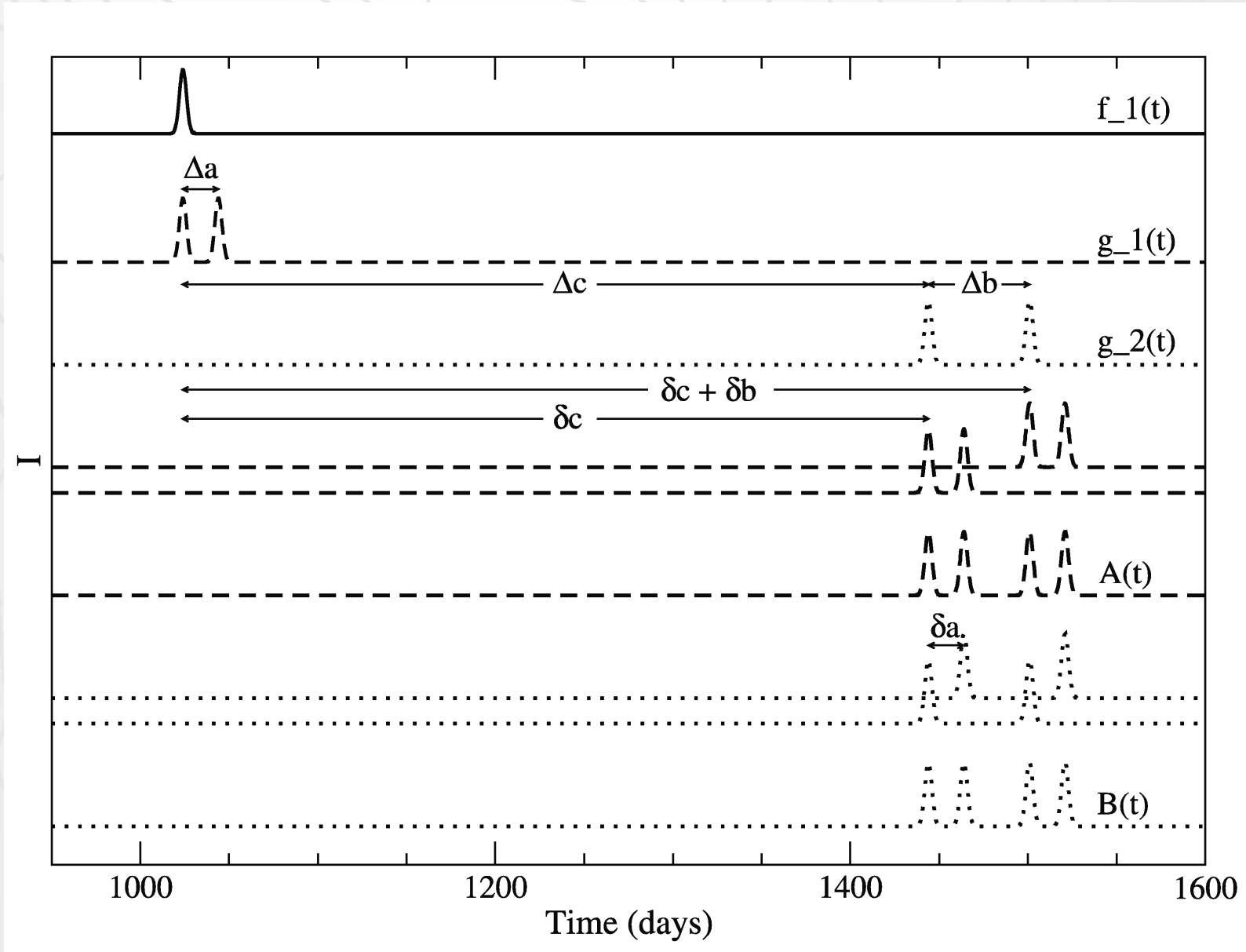
Assuming  $a_1 \approx a_2$ ,  $a_3 \approx a_4$ , we get:

$$g_1(t) = f_1(t) + f_1(t - \Delta a),$$

$$g_2(t) = f_1(t - \Delta c) + f_1(t - \Delta c - \Delta b),$$

where  $\Delta a = t_2 - t_1$ ,  $\Delta b = t_4 - t_3$ ,  $\Delta c = t_3 - t_1$

# Two blended images (graphical explanation)



# Two blended images - matching artificial blends

Artificial blends from observed data using trial delays

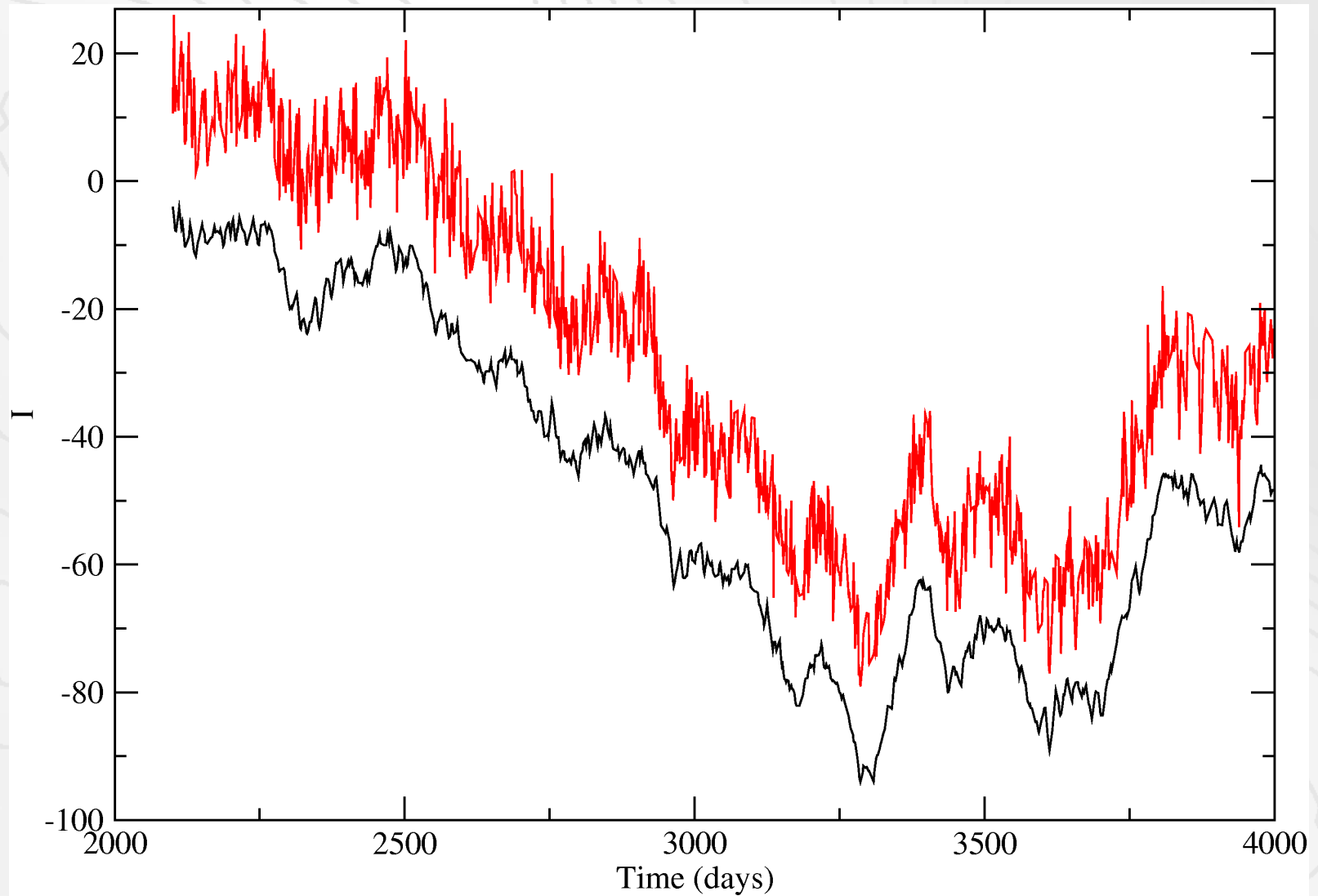
$\delta c, \delta a, \delta b$  :

$$A(t) = g_1(t - \delta c) + g_1(t - \delta c - \delta b),$$

$$B(t) = g_2(t) + g_2(t - \delta a)$$

# Moving to more realistic picture

- Sampled curves
- Noise



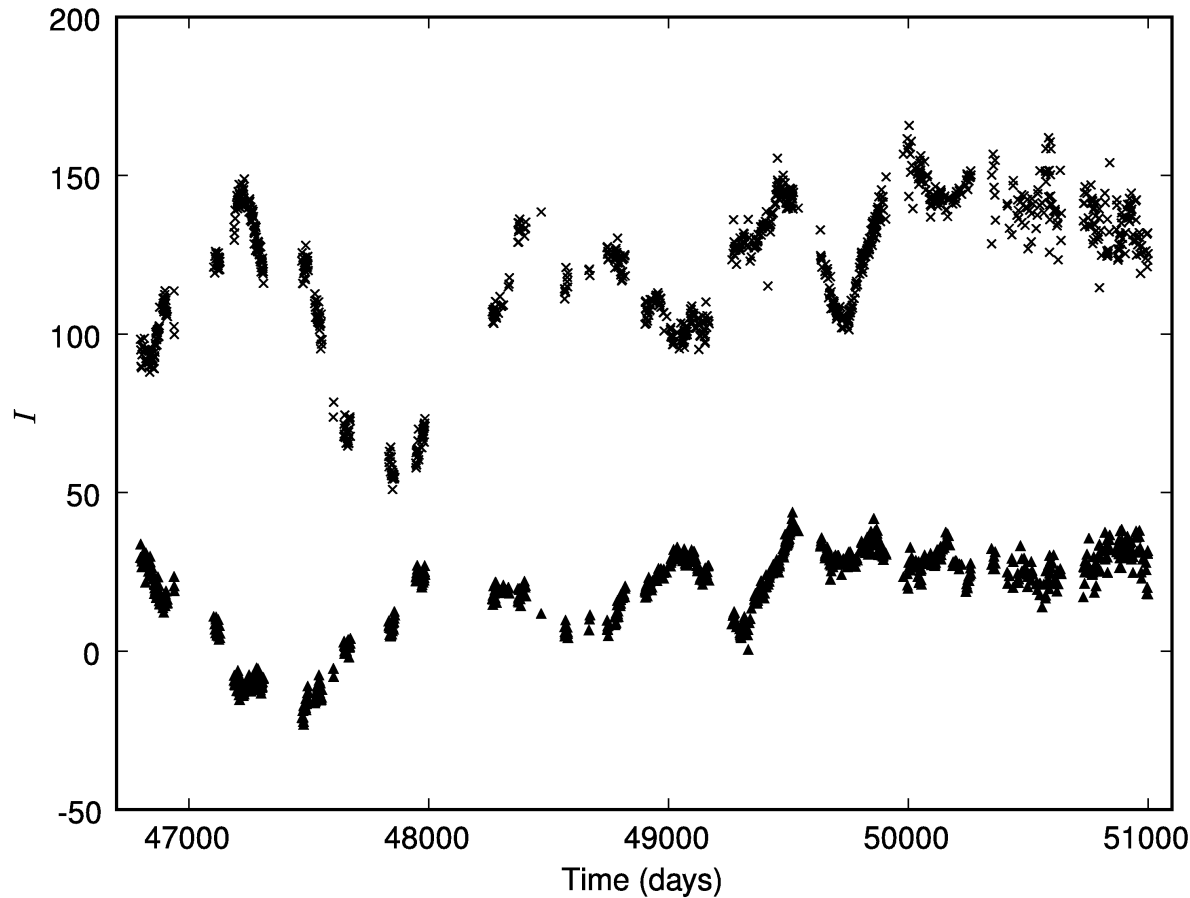
# Details of the method

- Simulating quasar variability to get test data
- Adding and subtracting sampled curves
- Statistic for measuring the difference of sampled curves
- Visual representation of the results

# Simulating quasar variability and blended data

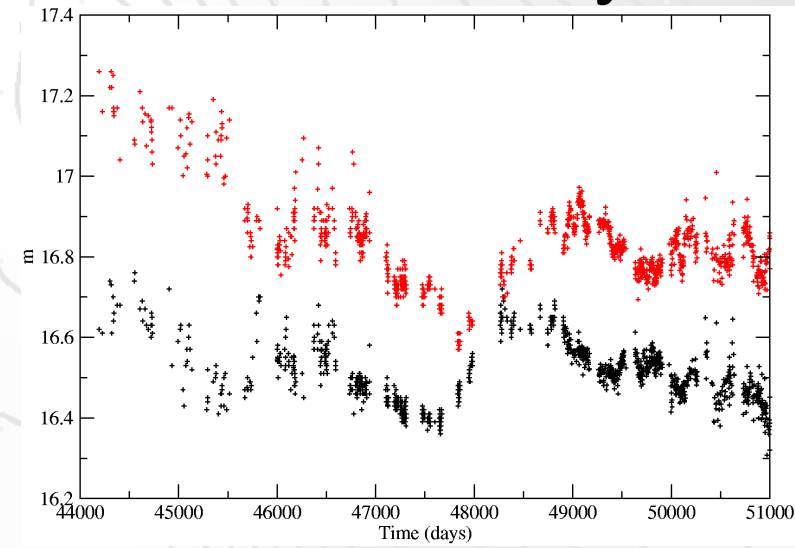
- Random walk:  $q(t_i) = q(t_{i-1}) \pm 1$
- Shifting in time
- Combining the blend
- Sampling

# A simulated time series (a clean image and a blend)

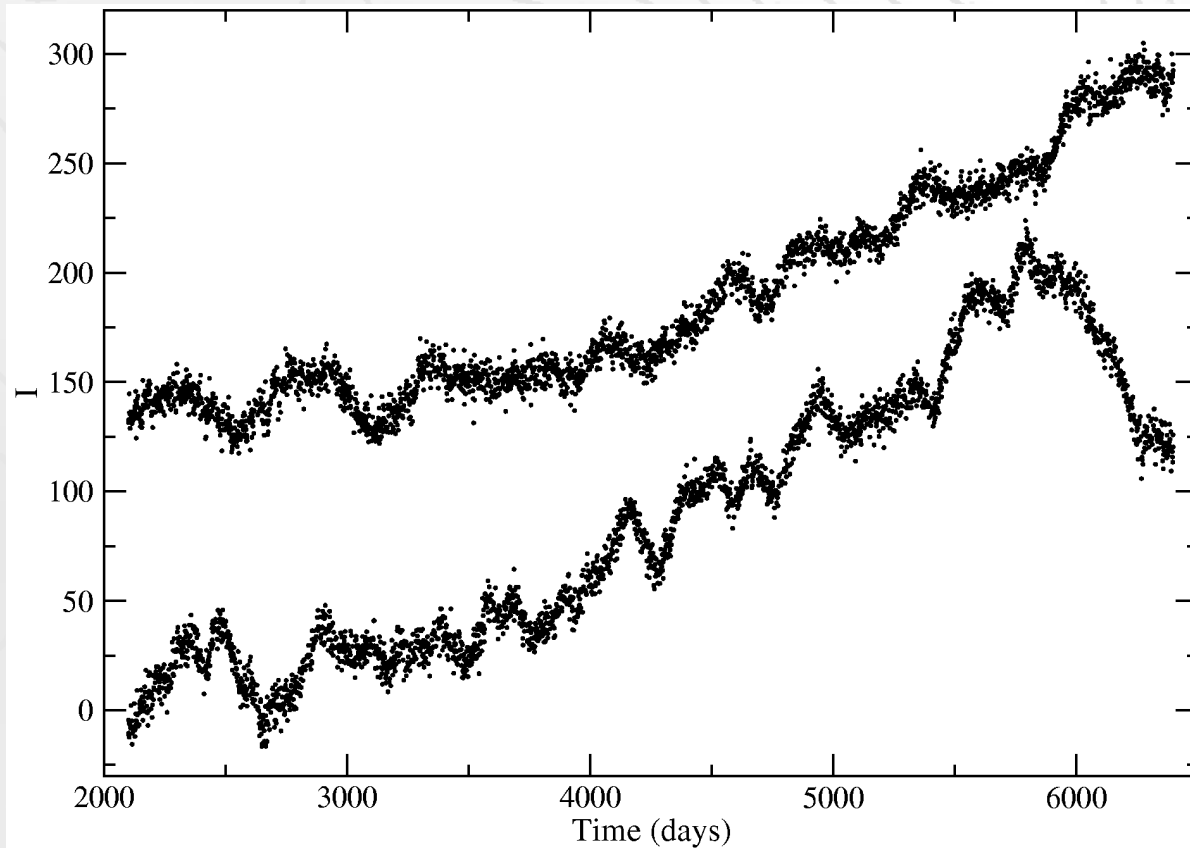


A random walk  
(lower curve) and a  
blend with Schild's  
sampling.

420.15, 20.21 days



# A simulated time series (two blended images)



Good sampling.  
420.2, 20.2 (lower),  
56.5 (upper) days

# Adding sampled curves to form the artificial blend from observed data

$$t_n, f_n, W_n, n=1,2,\dots, N$$

$$t_m, g_m, W_m, m=1,2,\dots, M$$

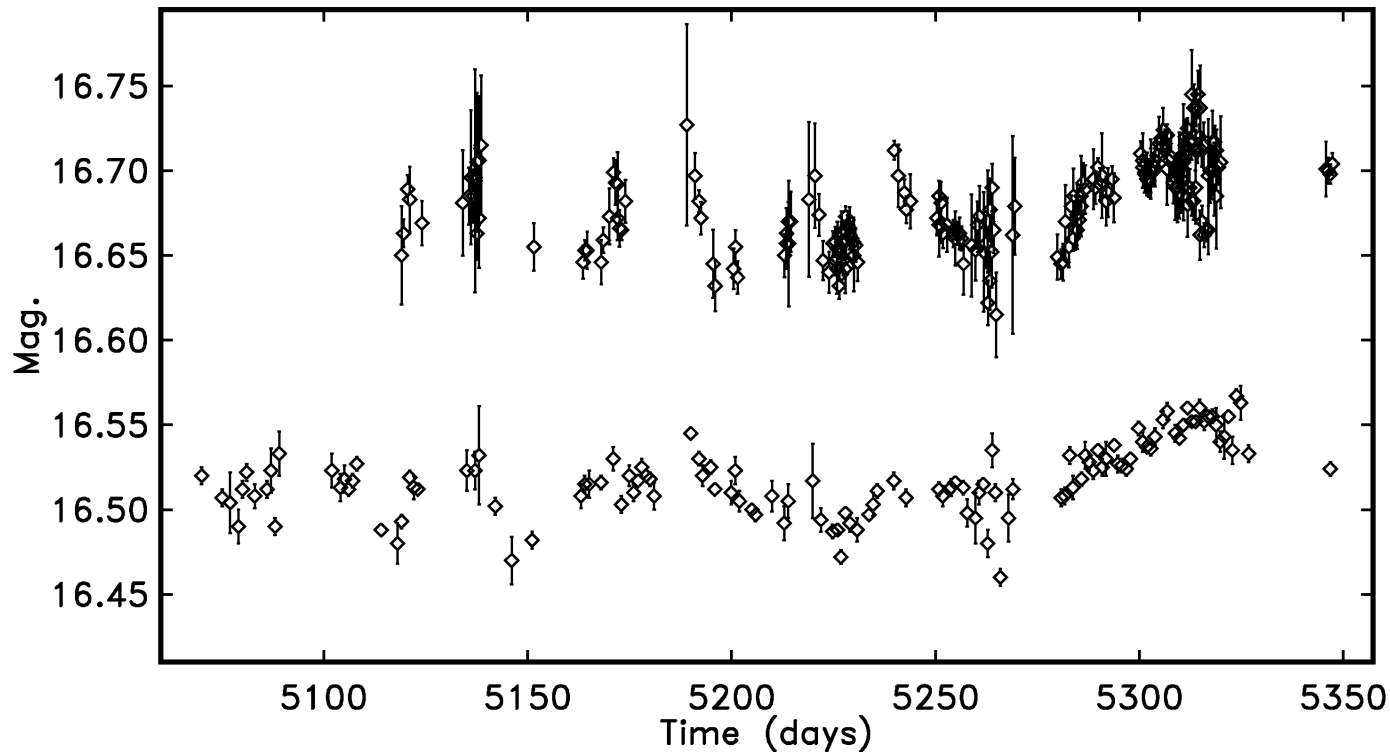
$$\frac{t_n + t_m}{2}, f_n + \alpha g_m, W_{n,m},$$

where the combined weights

$$W_{n,m} = S_{n,m} \frac{W_n W_m}{\alpha^2 W_n + W_m},$$

$$S_{n,m} = \begin{cases} 1 - \frac{|t_n - t_m|}{\sigma}, & \text{if } |t_n - t_m| \leq \sigma, \\ 0, & \text{if } |t_n - t_m| > \sigma. \end{cases}$$

# Adding sampled curves to form the artificial blend from observed data



**Fig. 1.** Combining an original time series with its shifted version. Depending on the spacing of time points and the downweighting parameter  $\sigma$ , the resulting series can be sparser (middle part of the series) or denser (right part). The combined error estimates are larger than the original (given) values.

# Subtracting sampled curves

$$t_n, f_n, W_n, n=1,2,\dots, N$$

$$t_m, g_m, W_m, m=1,2,\dots, M$$

$$\frac{t_n + t_m}{2}, (af_n + b - g_m)^2, W_{n,m},$$

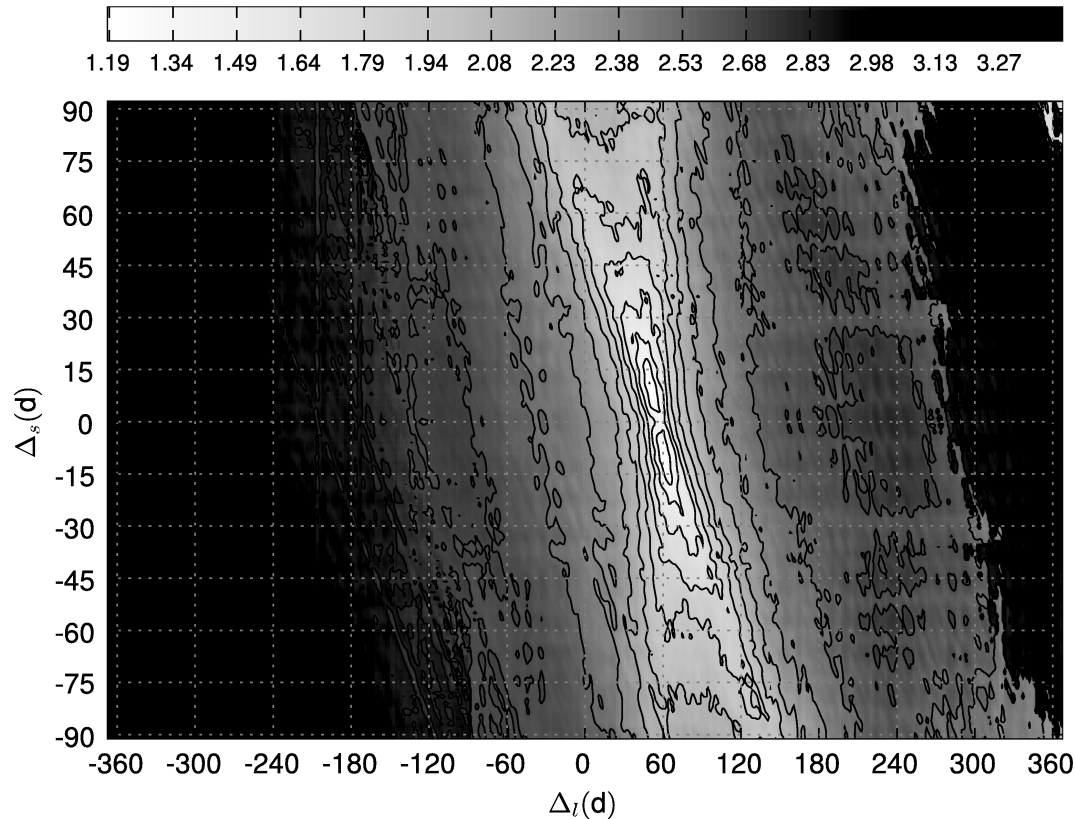
$$W_{n,m} = S_{n,m} \frac{W_n W_m}{W_n + a^2 W_m}$$

# Statistic for measuring the difference of sampled curves

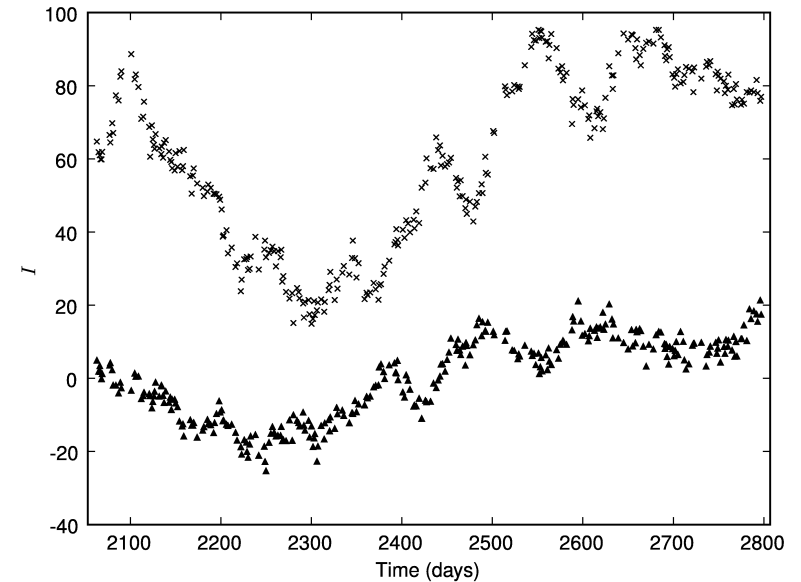
$$D^2 = \min_{a,b} \frac{\sum_{n,m} (af_n + b - g_m)^2 W_{n,m}}{\sum_{n,m} W_{n,m}}$$

We are going to search for the minimum of the statistic by varying trial delays (and magnification).

# Visual representation of the results (one blend)



**Fig. 2.** The two-dimensional grid of merit function values for a computer generated random walk and a blend computed from it. The general minimum must indicate the true pair of long and short delay values. The plot demonstrates degeneracy in full-scale computations well – there is obvious symmetry between the areas for positive and negative values of short delays. Values on the colour key represent the  $\log(D^2)$  and spacing of the contours. The same type of colour key is used in all two-dimensional plots.



**Fig. 3.** A basic computer-generated random walk  $C$  (lower curve) and a computer generated blend curve  $A$  ( $\Delta_l = 50.2$ ,  $\Delta_s = 10.6$ , the amplification parameter  $\alpha = 1.3$ ; we added 5% noise to both curves and shifted the blend up by 60 units).

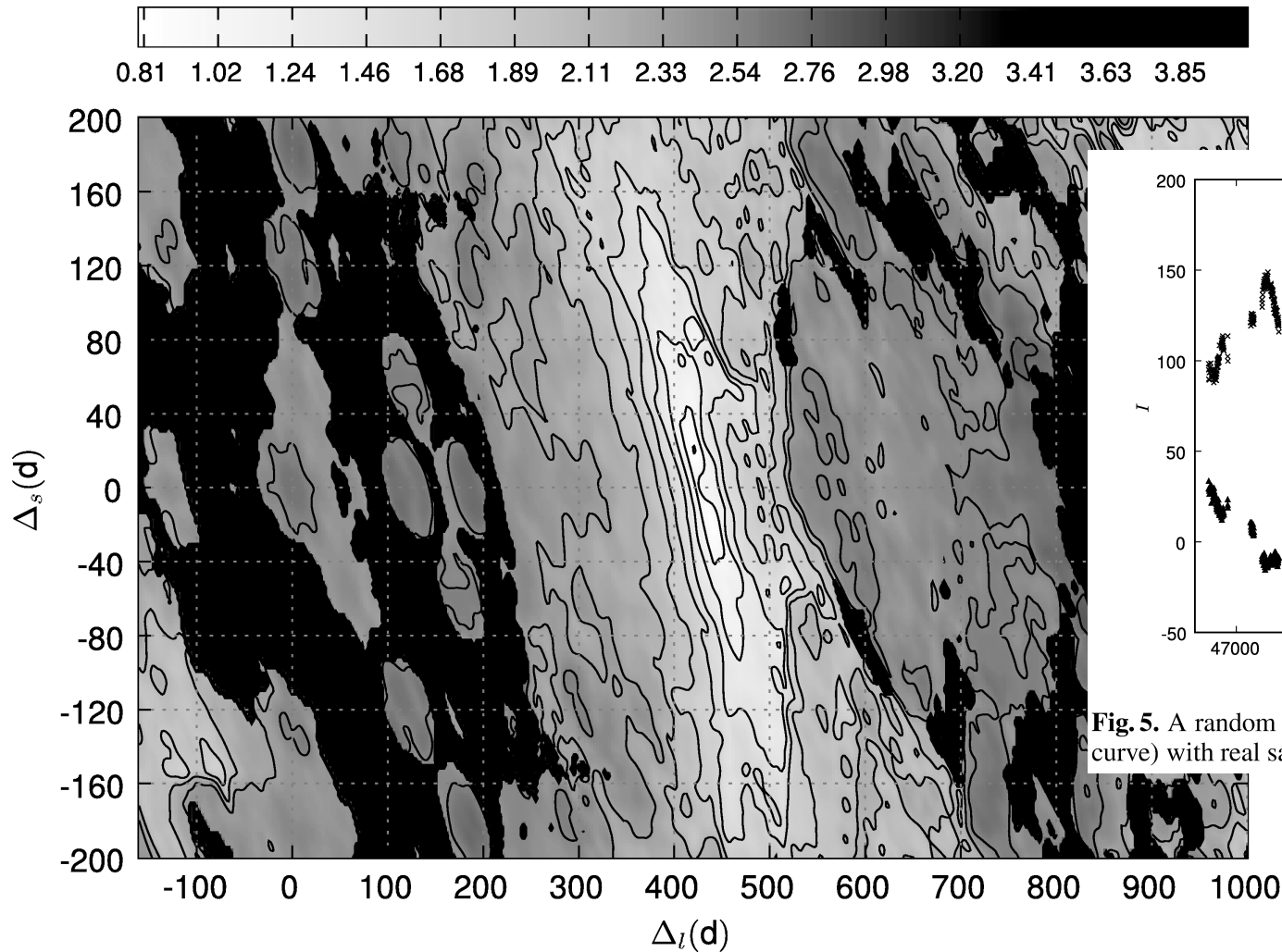
Random sampling, daylight caps.

Recovered parameters:

$\Delta_l = 50$  days,  $\Delta_s = 11$  days, and  $\alpha = 1.1$ .

Assuming pure curves, we get 59 days, which is incorrect answer.

# Visual representation of the results (one blend, Schild's sampling and errors)



420.15, 20.21, 0.8  
were put in

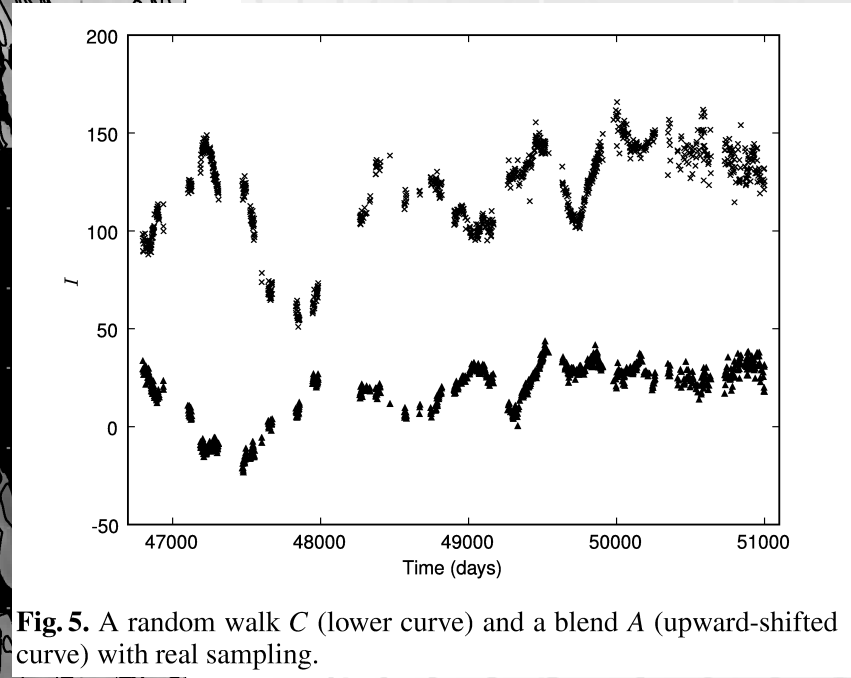
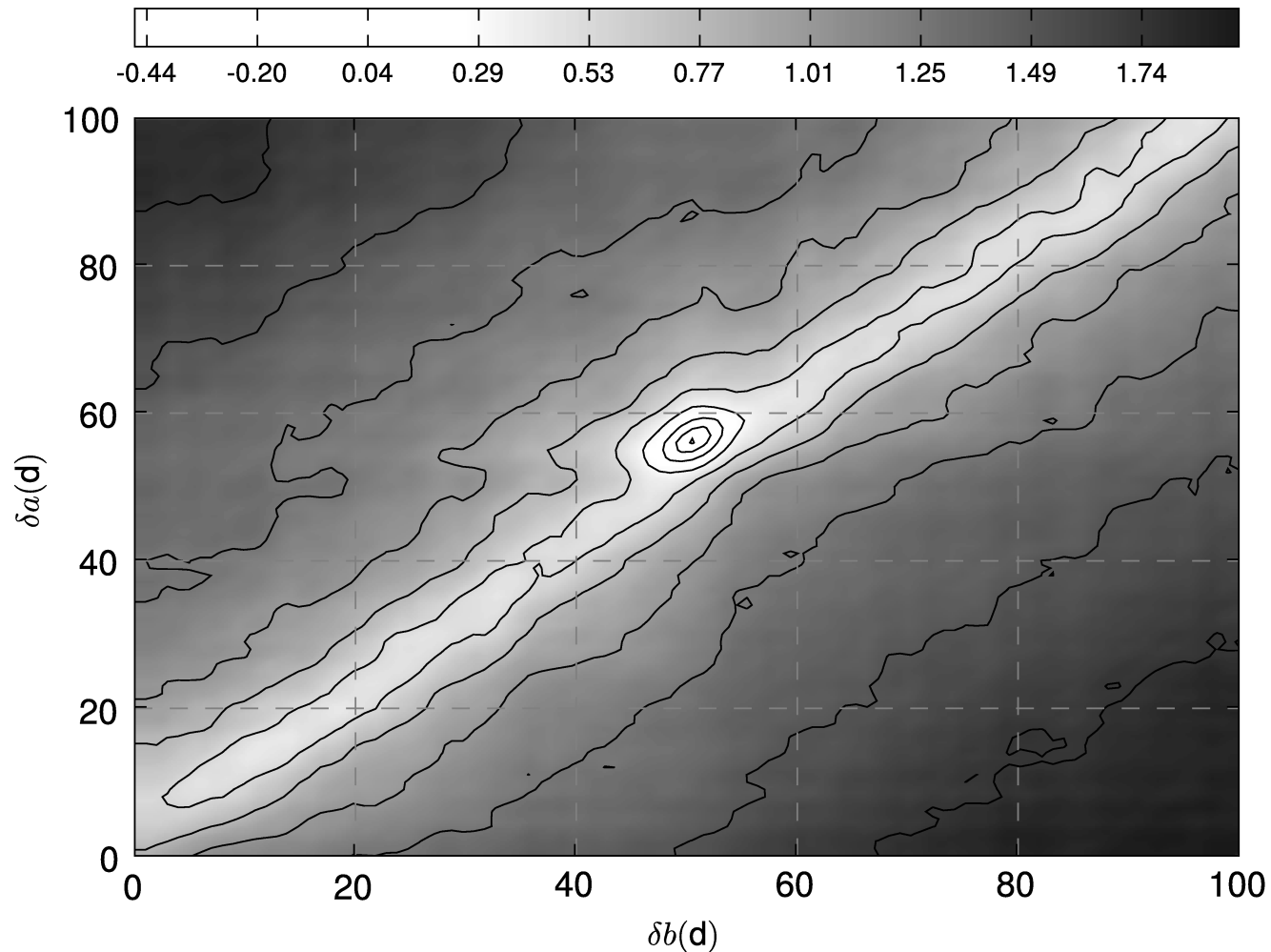


Fig. 5. A random walk C (lower curve) and a blend A (upward-shifted curve) with real sampling.

420.2, 20.0, 0.9 came  
out

Fig. 6. Merit function values for simulated data and real sampling.

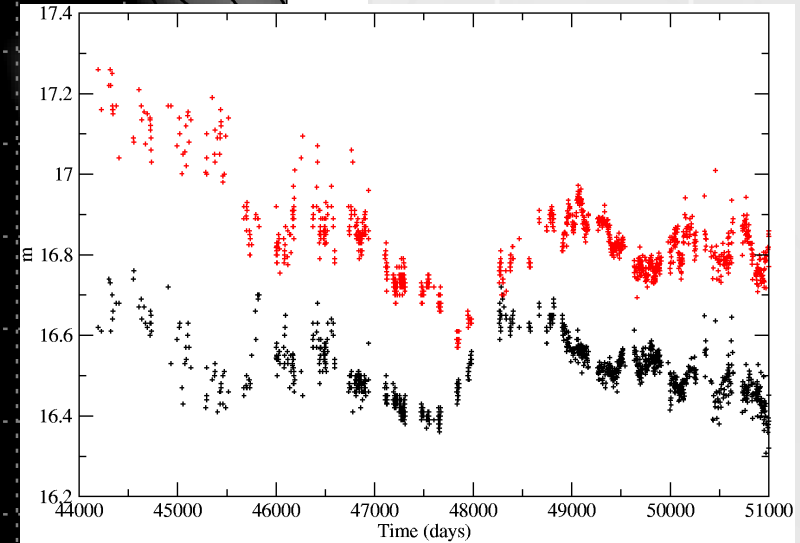
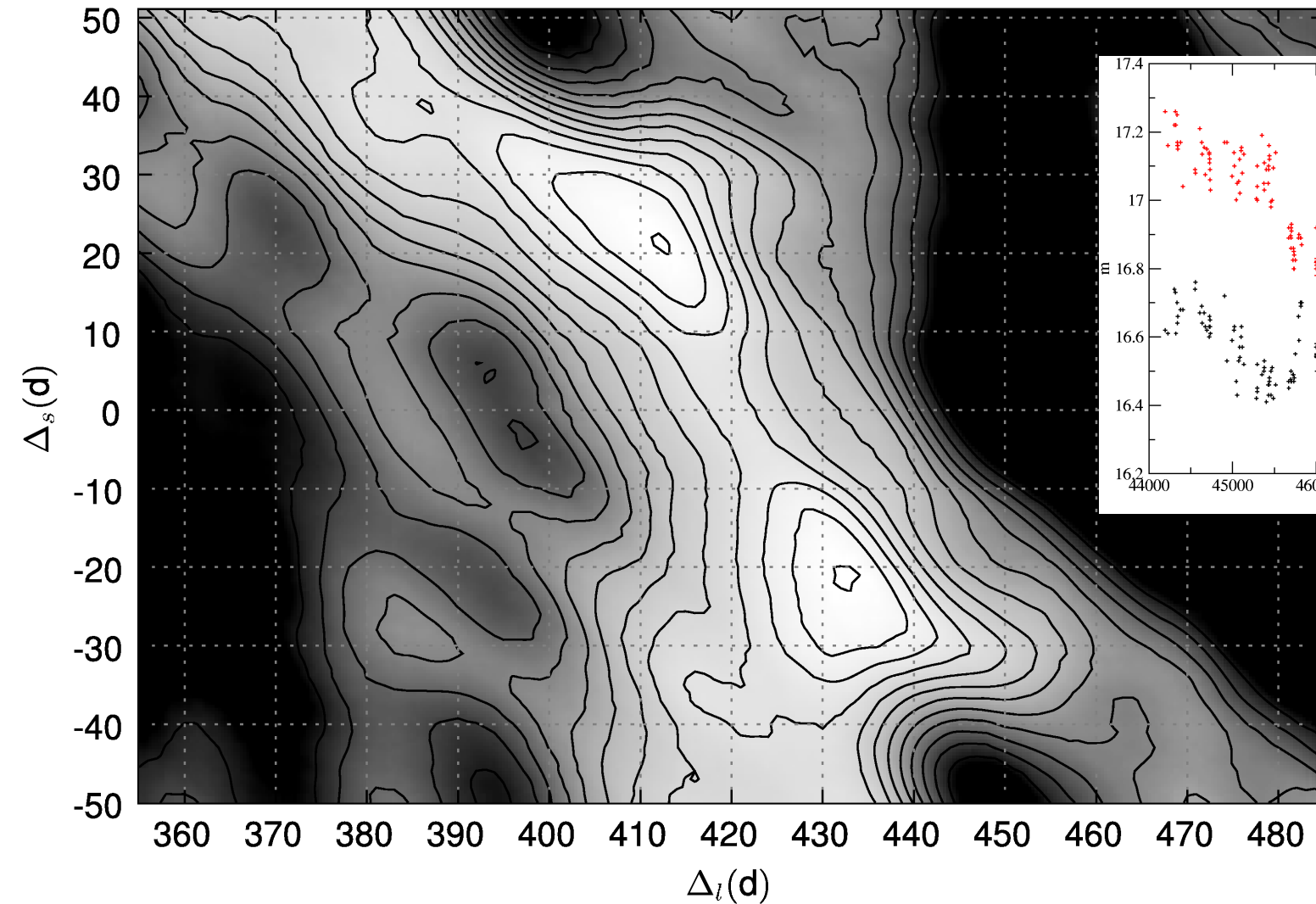
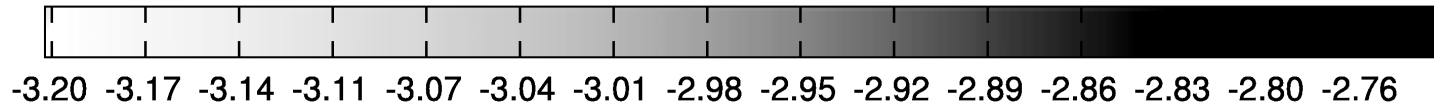
# Visual representation of the results (two blends)



- Even more degenerate
- Does not work if short delays are equal
- Higher S/N is needed

**Fig. 4.**  $D^2$  values for very close short delays.  $\Delta c = 420.2$ ,  $\Delta a = 56.5$ ,  $\Delta b = 50.1$  days and  $a = 0.8$ .

# Results from Schild's data



Assuming that B is blend, we got 412 and 22 days for time delays.

# What we were talking about.

- It is possible to find time delays from blended data using artificial blends
  - adding and subtracting blended data
  - statistic for measuring the difference of two time series that is insensitive to gaps

# References

- Hirv A., Eenmäe T., Liimets T., Liivamägi L. J., Pelt J. 2007, A&A, 464, 471
- Hirv A., Eenmäe T., Liivamägi L. J., Pelt J. 2007, Baltic Astronomy, 16, 241